

Input Output stability dates back the idea of internal or Lyapunov stability. The def and th. from state space lead to corresponding ip/op notions. However the converse is not true in general. We will need additional hypotheses.

$$\begin{cases} \dot{x}_1 = -x_1 + u \\ \dot{x}_2 = x_1^2 + x_2^2 \\ y = x_1 \end{cases}$$

One idea type of external stability says bounded ip shall always give bdd o/p.

$$\dot{x}_1(t) = \frac{dx}{dt} = -x_1 + u$$

$$\Rightarrow dx + x dt = u dt$$

$$\Rightarrow e^{t} dx + e^{t} x = e^{t} u dt$$

$$\Rightarrow e^{t} x(t) - e^{t_0} x_0 = \int_{t_0}^t e^{\tau} u(\tau) d\tau$$

$$\Rightarrow x_1(t) = e^{-(t-t_0)} x_1(t_0) + \int_{t_0}^t e^{-(t-\tau)} u(\tau) d\tau$$

$$y(t) = e^{-(t-t_0)} x_1(t_0) + \int_{t_0}^t e^{-(t-\tau)} u(\tau) d\tau$$

$$\|y(t)\| \leq \|x_1(t_0)\| + \int_{t_0}^t \|u(\tau)\| d\tau$$

→ Bounded ip will give you bdd o/p. But  $x_2$  blows up.

⇒ Introduce some basic notions and results of External stability and connect them to internal ⇒ Function spaces/Causality/Fb/WP/Passive

→ Cannot have infinite energy over an infinite time

$$S: [0, \infty) \rightarrow \mathbb{R}^m$$

• Truncation operator:  $(\cdot)_T, T \geq 0$

$$(S)_T(t) = \begin{cases} S(t) & t \leq T \\ 0 & t > T \end{cases}$$

•  $L_p$  Space:

$$L_p = \left\{ S: [0, \infty) \rightarrow \mathbb{R}^m \mid \int_0^\infty \|S(t)\|^p dt < \infty \right\}$$

• Extended  $L_p$  Space:

$$L_{pe} = \left\{ S: [0, \infty) \rightarrow \mathbb{R}^m \mid (S)_T \in L_p \forall T \geq 0 \right\}$$

$$L_p \subset L_{pe}$$

•  $S(t) = \begin{cases} 0 & t = 0 \\ 1/t & t > 0 \end{cases}$

$S \in L_{pe}$  but  $S \notin L_p$

We need extended  $L_p$  so that the integrals conv for trunc' for

•  $\forall p \in [1, \infty]$ ,  $L_{pe}$  is linear. If  $S \in L_{pe}$  then

—  $\|S_T(\cdot)\|$  is a non-dec fn. of  $T$ .

—  $S \in L_p$  iff  $\exists m > 0$  s.t.  $\|S_T\| \leq m \forall T \geq 0$

In that case,  $\|S\|_p = \lim_{T \rightarrow \infty} \|S_T\|_p$

Causal  $F: L_{pe}^m \rightarrow L_{pe}^n$  is said to be causal system if

$$(F(u))_T = (F(u_T))_T \quad \forall T \geq 0 \quad \forall u \in L_{pe}^m$$

→ Causality: Granger / ANI / transfer entropy

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⊙  $F: L_{pe}^m \rightarrow L_{pe}^r$  is causal iff  $\forall u_1, u_2 \in L_{pe}^m$ ,  
 $(u_1)_T = (u_2)_T$  for some  $T > 0 \Rightarrow (F(u_1))_T = (F(u_2))_T$

Stability: Finite Gain L-stability:

$F: L_{pe}^m \rightarrow L_{pe}^r$  is stable if  $\exists \underline{\alpha, \beta} > 0$  s.t. finite const.

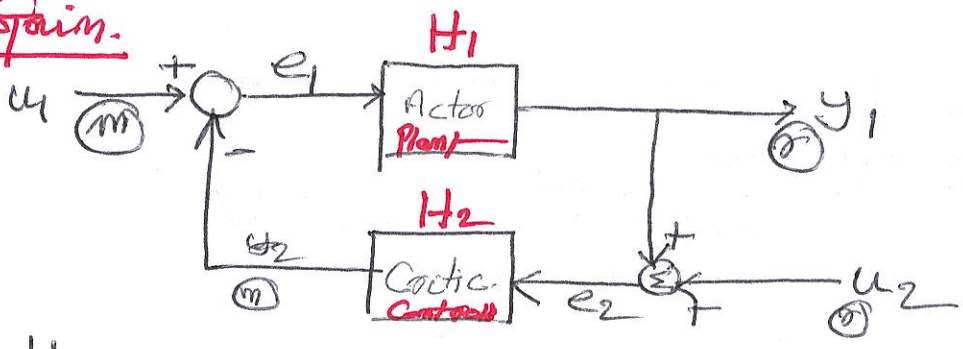
$$\| (F(u))_T \| \leq \gamma \| u_T \| + \beta$$

smallest such  $\gamma$  is called GAIN

Alternatively  $F$  is stable if

- ⊙  $u \in L_p^m \Rightarrow F(u) \in L_p^r$
- ⊙  $\exists$  finite const.  $\alpha, \beta$  s.t.  $\|F(u)\| \leq \alpha \|u\| + \beta \quad \forall u \in L_p^m$

Small Gain.



Example: set point Watts governor

- ⊙  $H_1, H_2$  are causal
- ⊙  $H_2$ 's are stable w/  $\alpha$ 's and  $\beta$ 's
- ⊙  $\forall u_1, u_2 \exists$  unique outputs  $e_1$  &  $e_2$ . Well Posed.

# Lect 16

Then if  $\alpha_1 \alpha_2 < 1$

$$\textcircled{i} \quad \| (e_1)_T \| \leq \left( \frac{1}{1 - \alpha_1 \alpha_2} \right) \left[ \| (u_1)_T \| + \alpha_2 \| (u_2)_T \| + \beta_2 + \alpha_2 \beta_1 \right]$$

$$\| (e_2)_T \| \leq \left( \frac{1}{1 - \alpha_1 \alpha_2} \right) \left[ \| (u_2)_T \| + \alpha_1 \| (u_1)_T \| + \beta_1 + \alpha_1 \beta_2 \right]$$

$\forall T \geq 0$  for any  $u_1, u_2 \in L_{pe}$

$\textcircled{ii}$  If  $u_1, u_2 \in L_p$  then  $(e_1, y_2)$   $(e_2, y_1) \in L_p$  and their norms are bounded w/o trace.

Interop. FB system is stable (FGLS) if  $\alpha_1 \alpha_2 < 1$ .

$\textcircled{iii}$  is hard to verify  $\Rightarrow$  stronger assumption.

$F: L_{pe}^m \rightarrow L_{pe}^n$  is incrementally FG.S if

$\textcircled{i}$   $F(0) \in L_{pe}^n$  (can be related to Lyap stable)

$\textcircled{ii}$   $\forall T > 0, u, v \in L_{pe}^m \exists k > 0$   $\leftarrow$  indep  $T, u, v$ .

$$\| (F_B(u_T))_T - (F_B(v_T))_T \| \leq k \| u_T - v_T \|^2$$

①  $F: L_{pe}^m \rightarrow L_{pe}^r$  is IFGS with gain  $k < 1$ .

Then,  $\exists$  unique  $u^* \in L_{pe}^m$   
 $F(u^*) = u^*$

②  $H_1(u)(t) = \int_0^t \exp(-a(t-\sigma)) u(\sigma) d\sigma$   
 $H_2(u)(t) = k u(t)$   $a > 0$

$\alpha_1 = \frac{1}{a}$   $\beta_1 = 0$   
 $\alpha_2 = |k|$   $\beta_2 = 0$   $\rightarrow \frac{|k|}{a} < 1$   
 $\rightarrow |k| < a$

$-a < k < a$  conservative.  
 $(k > -a)$  is  $(m+s)$  cond. 2

$N(u) \leq \|N(u) - N(0)\| + \|N(0)\|$

$\dot{q} = \frac{\partial H}{\partial p}$   $\dot{p} = -\frac{\partial H}{\partial q} + \mathcal{L}^{-1} \dot{p}$   
 o/p Optimized Lagrange  
grand disc.  
Hamiltonian.

Passive.  
Diss inequality  $\frac{dH}{dt} \leq \langle \dot{q}, f \rangle$

$\dot{x} = [J(x) - D(x)] \nabla_x H + B(x) u$

$y = B^T \nabla_x H$   $\dot{H} = \langle \nabla_x H, \dot{x} \rangle = -\nabla H^T D \nabla H + \nabla H^T B(x) u$